# **Improving 2D Human Pose Estimation in Rare Camera Views with Synthetic Data**



Automatic Face and **Gesture Recognition** 

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## Introduction

Methods and datasets for human pose estimation focus on side- and front-views.

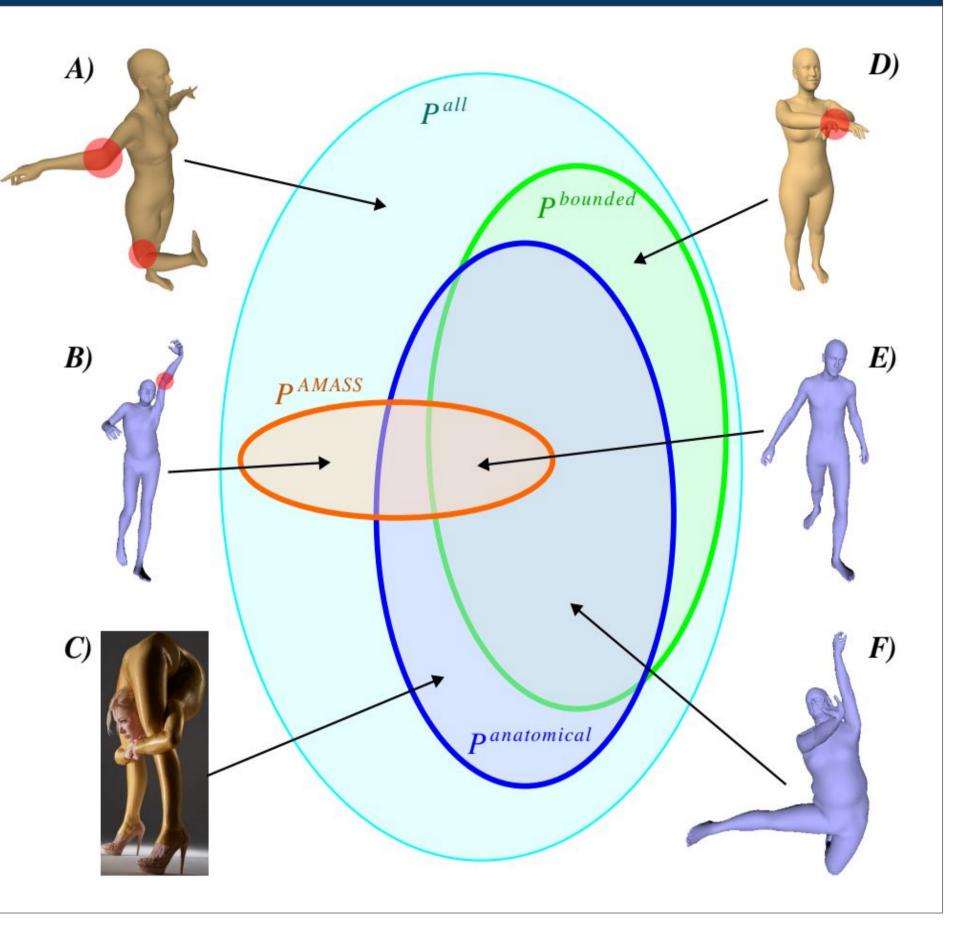
We propose RePoGen (RarE POses GENerator), SMPL-based method for generating an synthetic humans with comprehensive control of pose and view.

Experiments on real images with diverse poses show that, e.g., ViTPose, trained on COCO with added RePoGen data, outperforms prior art in top- and bottom-view pose estimation without performance loss on common views.

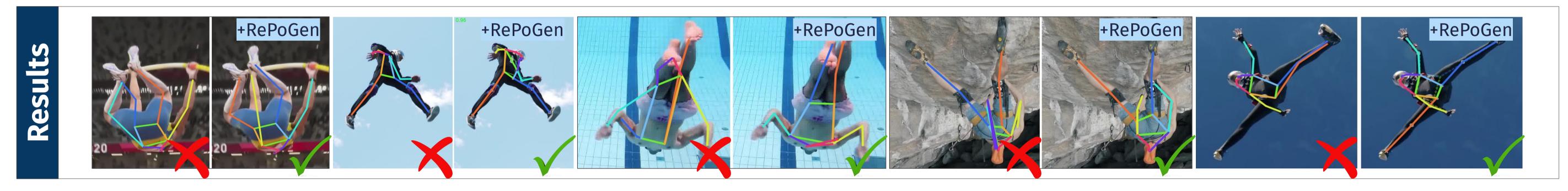
## RePoGen – a novel rare pose generation method

- each joint sampled independently
- ranges from physio textbook
- tradeoff between anatomical feasibility and novel poses that are hard to capture using MoCap systems
- a single distribution with parameters  $\alpha$ ,  $\beta$  and  $\theta$  models all joints

Right shoulder rotation	Right shoulder adduction	Neck flexion	Right elbow flexion
$\alpha = -20$ $\beta = 90$ $\theta = 0$	$\alpha = -140$ $\beta = 10$ $\theta = 0$ $\beta = 0$ $\beta = 0$ $\beta = 0$ $\beta = 0$ $\beta = 0$ $\beta = -125$ $\beta = -125$	$\alpha = -45$ $\beta = 45$ $\theta = 0$ $\theta = 0$ Angle [deg] 20 40 60	$\alpha = 0$ $\beta = 120$ $\theta = 0$ $\theta = 0$
$\circ P^{all}$	P <sup>all</sup> - All possible with SMPL		
<ul> <li>P<sup>anatomical</sup> - One human can achieve</li> </ul>			
$\circ P^{AMASS}$	- Capture	ed in AMASS	5
○ <b>P</b> <sup>bounded</sup>	- Genera	ted by RePo	oGen



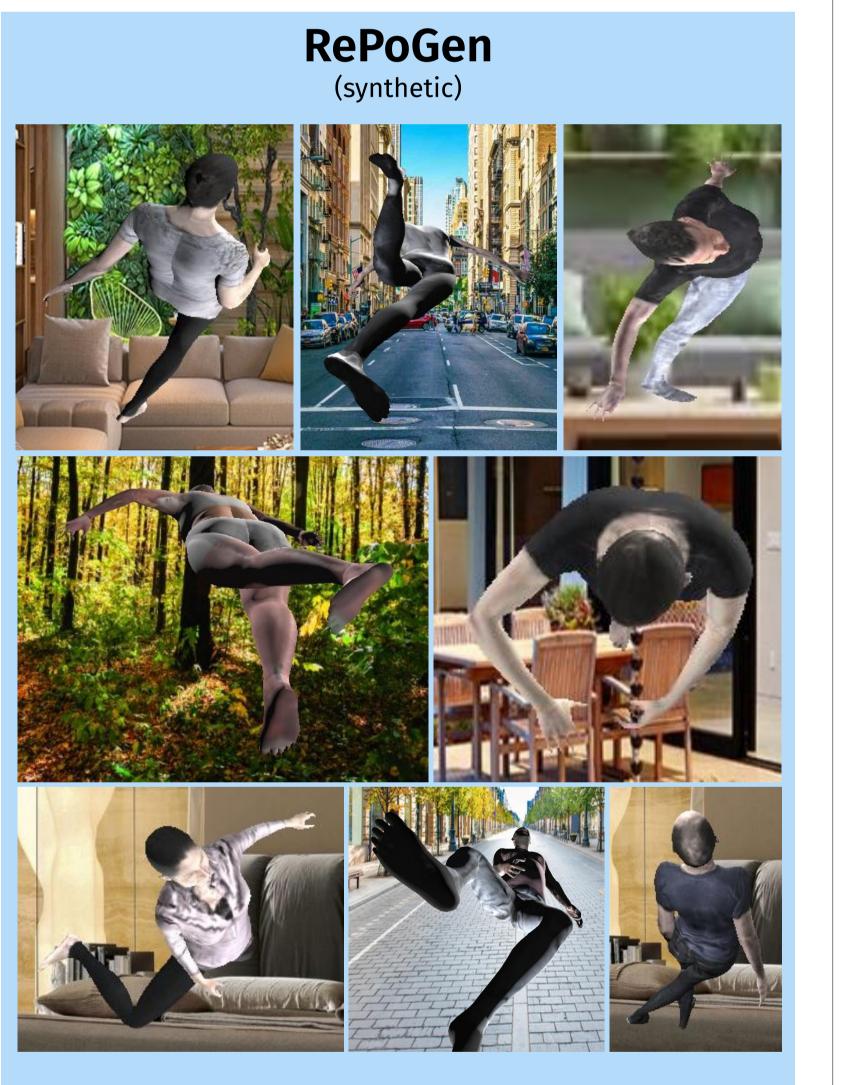
Ablation shows that anatomical plausibility, a focus of prior research, is not a prerequisite for effective performance.



#### Datasets

**RePo** includes high percentage of top- and bottom-view images of rare poses despite having fewer images than previous datasets.

Existing **Datasets**: only PoseFES and available, WEPDTOF-Pose both capturing common poses from ceiling-mounted fisheye



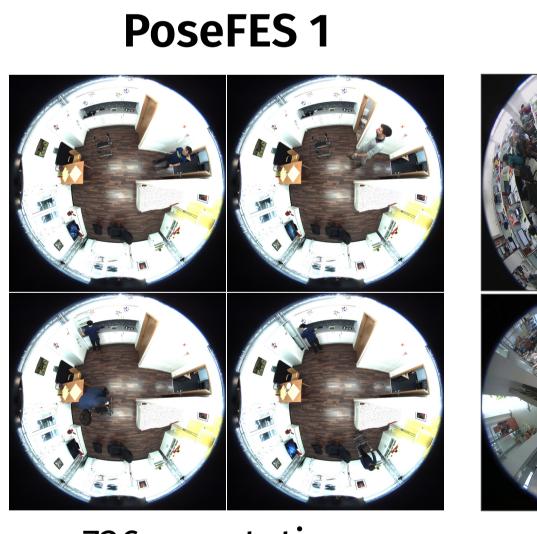
## **Performance Evaluation**

#### ViTPose trained on RePoGen performs:

- Better than THEODORE+ and AMASS Poses
- The difference is more evident on RePo
- Keeps SOTA performance on orbital views

ViTPose trained on ■ COCO ■ AMASS ■ RePoGen

cameras.



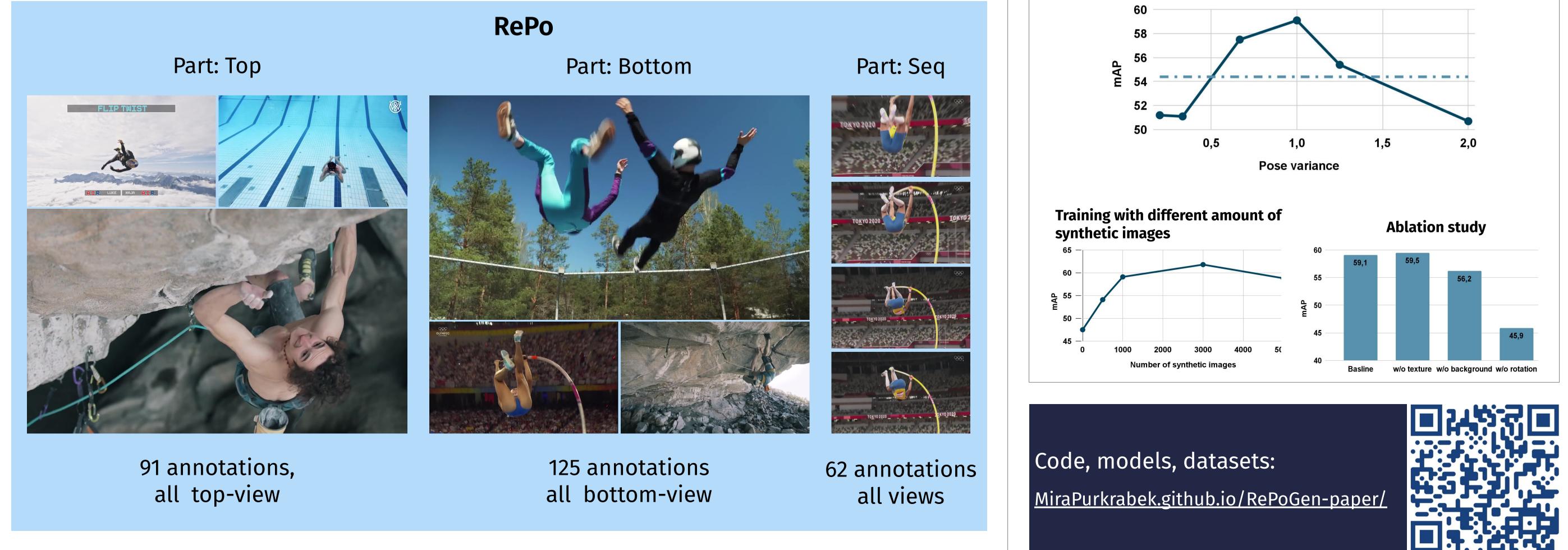
#### 736 annotations 76 top-view

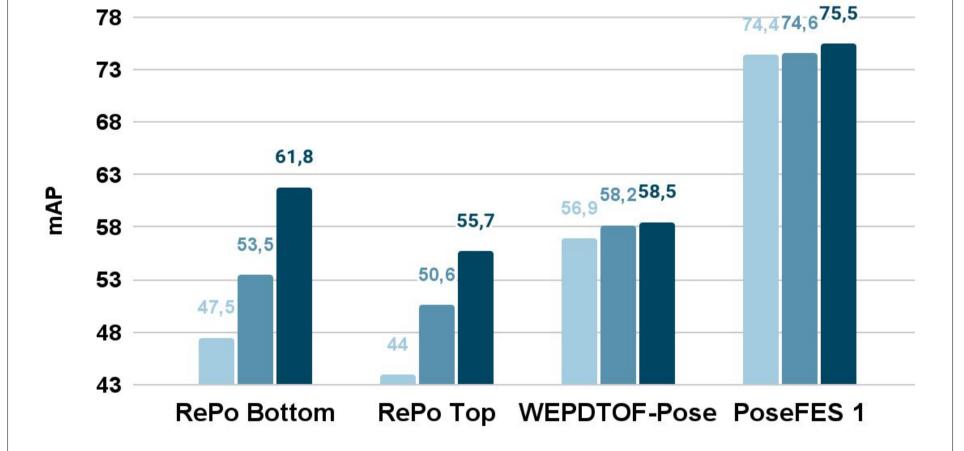
### WEPDTOF-Pose



6749 annotations 67 top-view

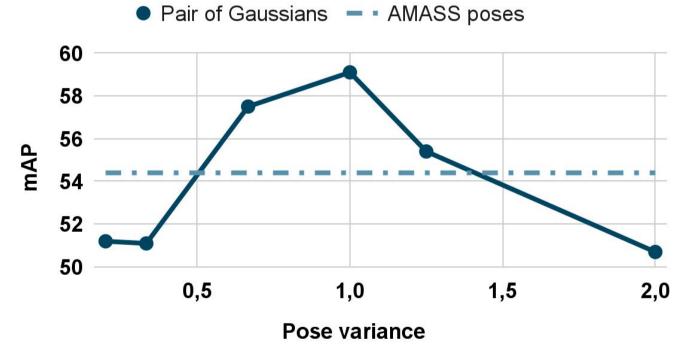
3000 annotations all top or bottom view





#### Ablation study

- Both too "unrealistic" and too many common poses hinder training.
- Synthetic images create domain gap
- $\circ$  Visual realism  $\leq$  data diversity.



Training with different pose variance

This work was supported by the Technology Agency of the Czech Republic project No. SS05010008, Ministry of the Interior of the Czech Republic project No. VJ02010041 and Czech Technical University student grant SGS23/173/OHK3/3T/13.